

S.1(FE.1) Engineering Simulation

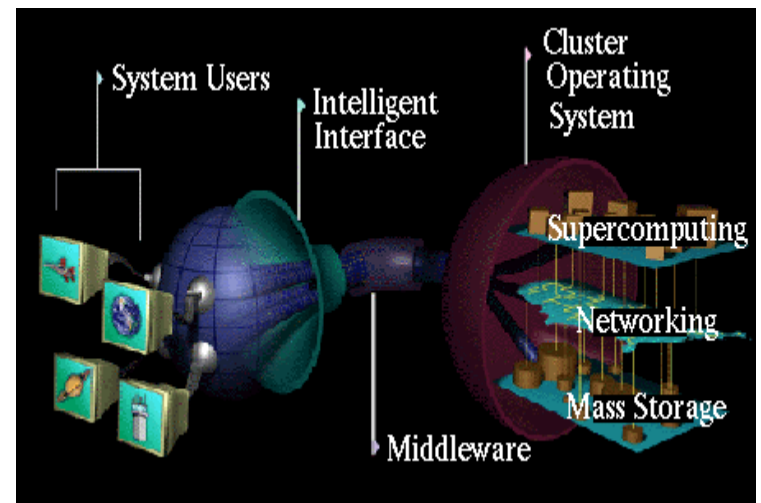
Physical Laboratory:

- *model* the geometry
similitude
cost
- *measure* the data
interpolation (errors)
interpretation



Computational Laboratory:

- *model* the mathematics
conservation, BCs
- *model* the physics
complexity, cost
- *compute* the data
approximation error
physics model error
interpretation



S.2(FE.10) Summary, Finite Element Analysis

For arbitrary geometries and non-linearity

problem statement: $\mathcal{L}(q) = 0$ on $\Omega \subset \mathbb{R}^n$ + BCs

approximation: $q(\mathbf{x}) \approx q^N(\mathbf{x}) \equiv \sum_{\alpha}^N \Psi_{\alpha}(\mathbf{x}) Q_{\alpha}$

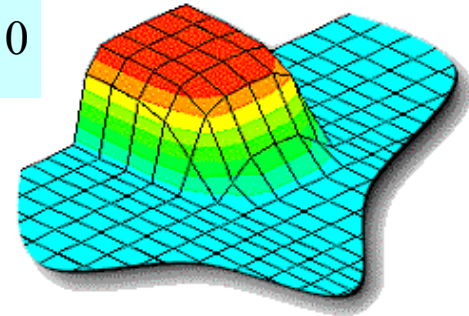
error minimization: $\text{GWS}^N = \int_{\Omega_e} \Psi_{\alpha}(\mathbf{x}) \mathcal{L}(q^N) d\tau \equiv 0$

FE discretization: $\Omega \approx \Omega^h = \cup_e \Omega_e$

$$q^N \equiv q^h = \cup_e \{N(\mathbf{x})\}^T \{Q\}_e$$

FE GWS^h: [Matrix] { Q } = { b }

error quantization: refined Ω^h solutions



S.3(PS.12) Computational Simulation

Engineering design problems: PDEs + physics + BCs

unknown called *state variable* $\equiv q(\mathbf{x}, t)$

solution is distribution of q on $(\mathbf{x}, t > t_0)$
analytically *intractible!*

Computer simulation \Rightarrow seek an *approximate* solution

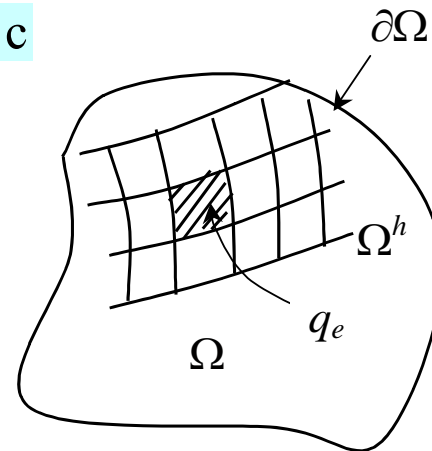
$$q(\mathbf{x}, t) \approx q^N(\mathbf{x}, t)$$

finite difference - historical, archaic

finite element analysis

$$q^N(\mathbf{x}, t) \equiv q^h(\mathbf{x}, t) = \cup_e q_e(\mathbf{x}, t)$$

optimal
encompassing
real world problems



S.4(HT1.18) Error Estimation, Energy Norm

Improved error estimate uses entire solution via a “norm”

$$\text{energy norm} \equiv \|T\|_E^h \equiv \frac{1}{2} \int_{\Omega} k \frac{dT^h}{dx} \frac{dT^h}{dx} d\tau \Rightarrow \frac{1}{2} \sum_e^M \{Q\}_e^T [\text{DIFF}]_e \{Q\}_e$$

Uniform mesh refinement study

$$\|T^h\|_E + \|e^h\|_E = \|T\|_E = \|T^{h/2}\|_E + \|e^{h/2}\|_E = \dots$$

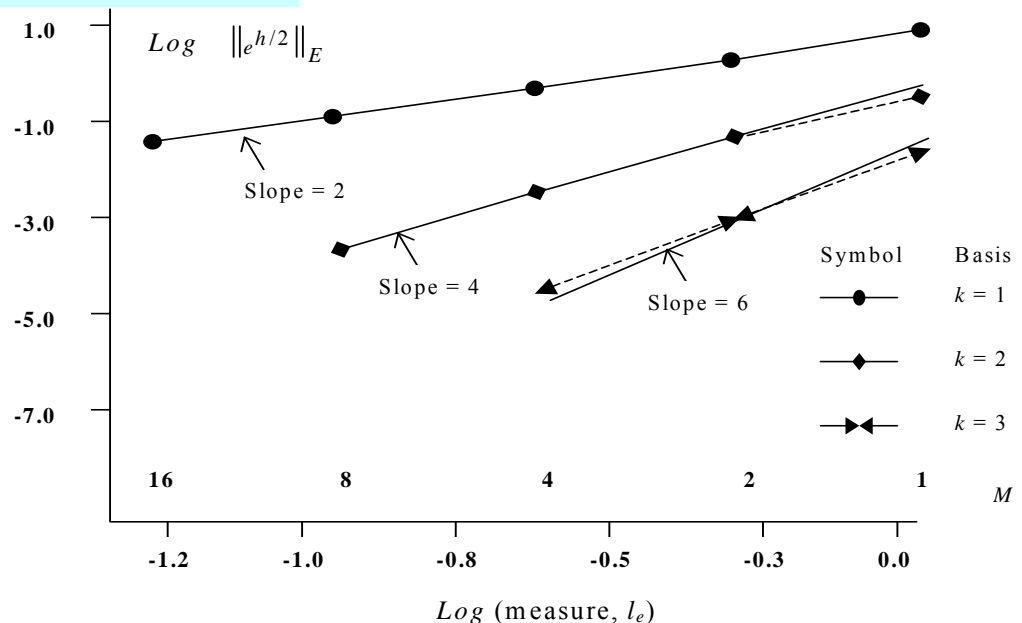
$$\text{asymptotic convergence: } \|e^h\|_E \leq C_k \ell_e^{2k} \|\text{data}\|_{L2}^2$$

error estimator

$$\|e^{h/2}\|_E = \frac{\Delta \|T^{h/2}\|_E}{2^{2k} - 1}$$

confirmation of theory

$$\text{slope} = \frac{\log \|e^{h/M}\|_E / \|e^{h/2M}\|_E}{\log 2}$$



S.5(HT1.28) DE GWS^h Summary, $n = 1$

Given DE + BC problem statement on $n = 1$

$$\mathcal{L}(q) = 0 \text{ on } \Omega \subset \mathbb{R}^1, \quad \ell(q) = 0 \text{ on } \partial\Omega$$

FE weak statement recipe

approximation:

$$T(x) \approx T^N(x) \equiv T^h(x) = \cup_e T_e(x)$$

FE basis:

$$T_e(x) = \{N_k(\zeta)\}^T \{Q\}_e$$

error extremization:

$$\text{GWS}^N = \int_{\Omega} \Psi_{\beta}(x) \mathcal{L}(T^N) dx \equiv \{0\} \Rightarrow \text{GWS}^h = S_e \{\text{WS}\}_e$$

matrix statement:

$$\{\text{WS}\}_e = ([\text{DIFF}]_e + [\text{BCs}]_e) \{Q\}_e - \{\mathbf{b}(\text{data})\}_e$$

error estimation:

$$\|e^h\|_E \leq C \ell_e^{2\gamma} \|\text{data}\|_{L_2}^2, \quad \gamma \equiv \min(k + 1 - m, r - m)$$

FE *template* pseudo-code

$$\{\text{WS}\}_e = (\text{const}) (\text{avg})_e \{\text{dist}\}_e^T (\text{metric})_e [\text{FE matrix}] \{Q \text{ or data}\}_e$$

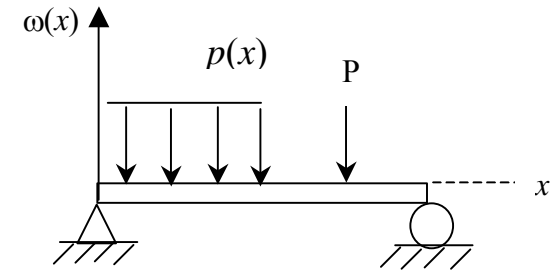
S.6(CM1.10) E-B, T Beams, GWS^h Accuracy/Convergence

GUI creates Matlab script for either theory

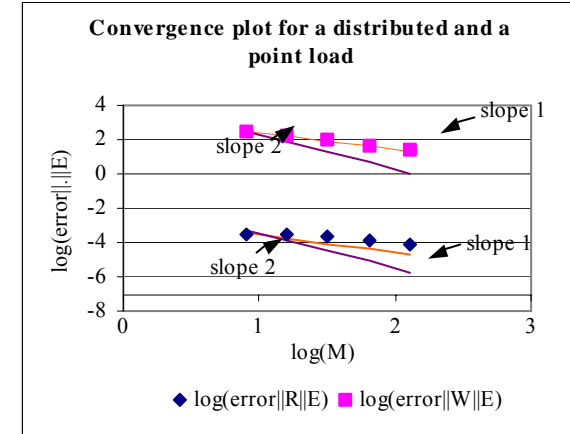
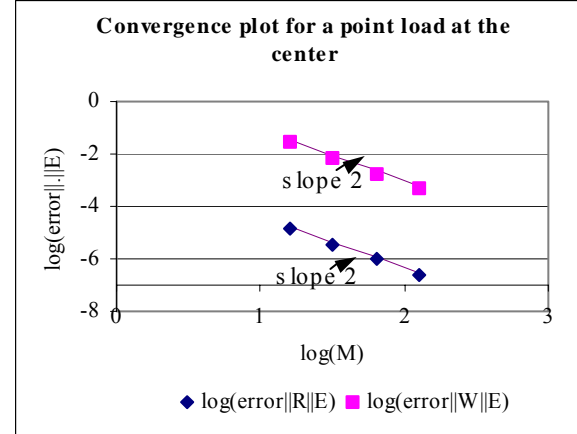
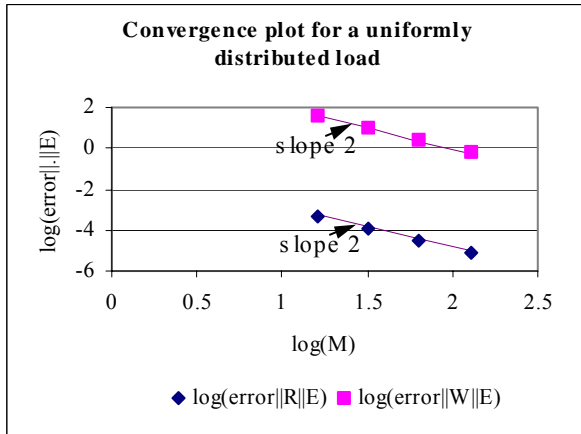
theory:

$$\|e^h\|_E \leq C \ell_e^{2\gamma} \|\text{data}\|_{L2}^2$$

$$\gamma \equiv \min(k, r-1)$$

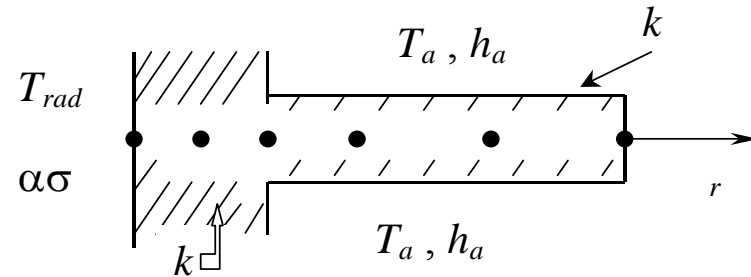
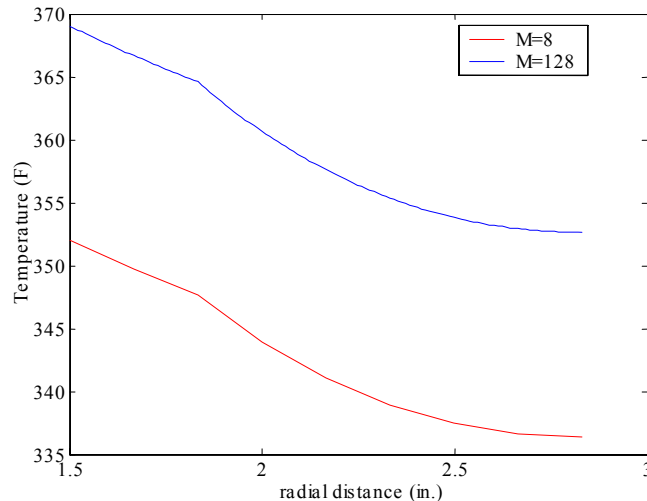


accuracy/convergence experiments



S.7(CM1.27) IC Cylinder, Accuracy, Convergence

GWS^h {N₁} basis implementation, temperature distributions



Convergence:

$$\|e^h\|_E \leq Cl_e^{2\gamma} \|\text{data}\|_{L^2}^2, \quad \gamma = \min(k, r-1)$$

Energy norm convergence data, $k = 1$

Mesh	M	$\ T\ _E$	slope
h	8	2.36494E+03	
$h/2$	16	2.42266E+03	
$h/4$	32	2.45369E+03	0.89486
$h/8$	64	2.46981E+03	0.94566
$h/16$	128	2.47802E+03	0.97236

Energy norm convergence, [HBC] on all elements

Mesh	M	$\ T\ _E$	slope
h	8	2.28175700E+03	
$h/2$	16	2.28230949E+03	
$h/4$	32	2.28244772E+03	1.99890
$h/8$	64	2.28248228E+03	1.99972
$h/16$	128	2.28249092E+03	1.99993

S.8(HTn.34) Summary, n -D GWS^h Essence for DE

FE discrete implementation GWS^h for steady DE

“recipe” \Rightarrow analytical transformation of PDE plus BCs to algebraic (computable) form

analogous \Rightarrow transformation methods for linear PDEs

solution^h \Rightarrow parametric function of Re, Gr, Pr, Nu and *data*

error^h \Rightarrow controllable via Ω^h and $\{N_k(\zeta, \eta)\}$ selections

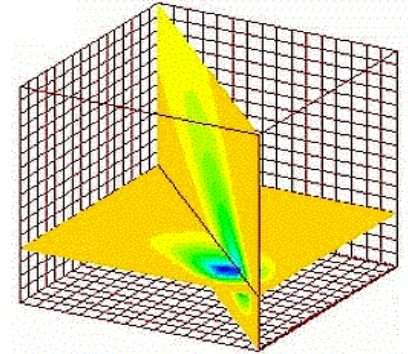
$$\|e^h\|_E \leq Ch^{2\gamma} \|\text{data}\|_{L_2}^2$$

$$\gamma \equiv \min(k + 1 - m, r - m)$$

S.9(CD1.2) Unsteady Scalar Transport

Eulerian non-D description for scalar transport

$$\begin{aligned} \mathcal{L}(q) &= \frac{\partial q}{\partial t} + \mathbf{u} \cdot \nabla q - \text{Pa}^{-1} \nabla \cdot (1 + \text{Pa}^t) \nabla q - s = 0, \quad \text{on } \Omega \times t \\ \ell(q) &= \nabla q \cdot \mathbf{n} + \text{Pb}(q - q_{ref}) + f_n = 0, \quad \text{on } \partial\Omega_r \times t \\ q(\mathbf{x}_b, t) &= q_b(\mathbf{x}_b, t), \quad \text{on } \partial\Omega_b \times t \\ q(\mathbf{x}, t_0) &= q_0(\mathbf{x}), \quad \text{on } \Omega \cup \partial\Omega \times t_0 \end{aligned}$$



Definitions for (\mathbf{x}, t) , Pa, Pb, Pa^t depend on application

Transport	q	Pa	Pb	Pa^t	} $\text{Re}^t \equiv \left(\frac{v^t}{v} \right)_{\text{dim}}$
heat	Θ	RePr	Nu	Re^t/Pr^t	
mass	Y	ReSc	Pa^{-1}	Re^tSc^t	
pollutant	Y_α	ReSc	Pa^{-1}	Re^tSc^t	

S.10(CDn.21) Unsteady $n - D$ Scalar Transport

Essential ingredients of $GWS^h (mDE) + \theta TS$

approximation: $q(\mathbf{x}, t) \approx q^N(\mathbf{x}, t) \equiv q^h(\mathbf{x}, t) = \cup_e q_e(\mathbf{x}, t)$

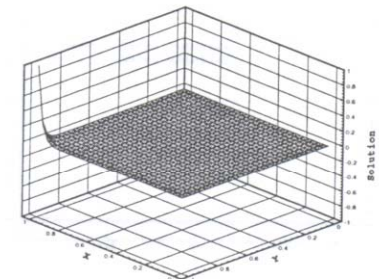
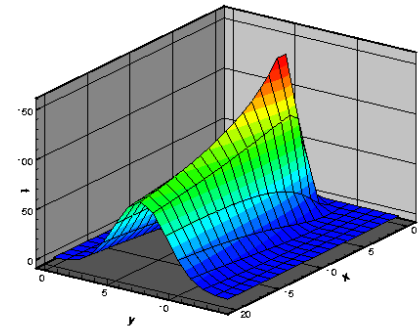
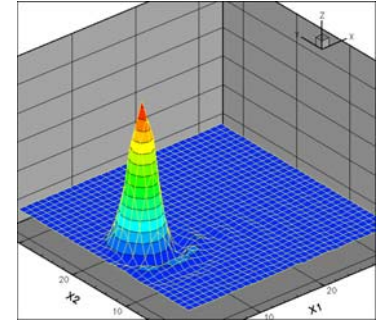
FE basis: $q_e(\mathbf{x}, t) = \{N_k(\zeta, \eta)\}^T \{Q(t)\}_e$

error extremization: $GWS^N = \int_{\Omega} \Psi_{\beta}(\mathbf{x}) \mathcal{L}^m(q^N) d\tau \equiv \{0\} \Rightarrow GWS^h$

matrix statement: $GWS^h + \theta TS \Rightarrow [mJAC]\{\Delta Q\} = -\Delta t\{mRES\}$
 $[mJAC] = S_e([mJAC]_e), \quad \{mRES\} = S_e(\{mRES\}_e)$

asymptotic convergence: $\|e^h(t)\|_E \leq Ch_e^{f(k, Pe, \beta)} \|data\|_{L2}^2 + C_t \Delta t^{f(\theta)} \|q_0\|_E$

error spectra: $U_{\omega} \& G \Rightarrow f(\omega, k, h, \Delta t, \theta, \alpha, \beta, \gamma)$



Template pseudo-code converts theory \Rightarrow practice

$GWS^h(mDE) + \theta TS \Rightarrow S_e \{WS\}_e \equiv \{0\}$

$\{WS\}_e \equiv (\text{const})(\text{avg})_e \{\text{dist}\}_e (\text{metric})[\text{Matrix}]_e \{Q \text{ or data}\}_e$

$[JAC]_e \equiv \partial \{WS\}_e / \partial \{Q\}_e$

S.11(CMn.19) Plane Stress: Plate with a Hole

GWS^h for DP and/or DE extremum, plane stress, $n = 2$

$$[\text{Matrix } (\mathbf{E}, \nu)] \begin{Bmatrix} U \\ V \end{Bmatrix} = \{\mathbf{R}(\varepsilon_0, \tau_0, \mathbf{T}, \mathbf{P}, \rho g)\}$$

Computer lab design study

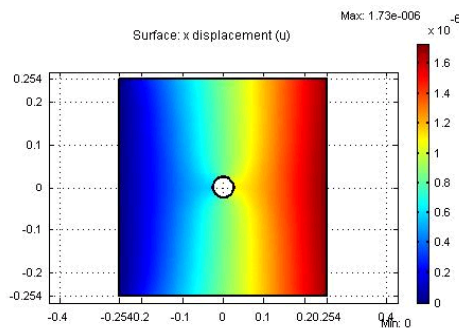
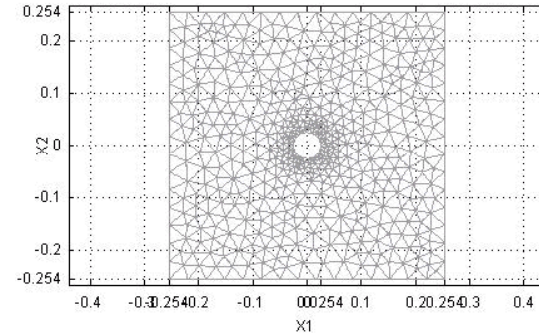
geometry: plate with hole in tension

data: $L, D, \mathbf{T}, \text{BCs}$

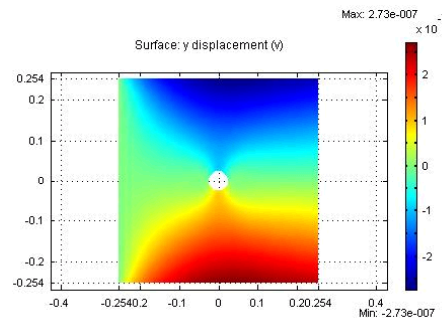
solution: $u^h(x, y), v^h(x, y)$

interpretation: von Mises stress concentration

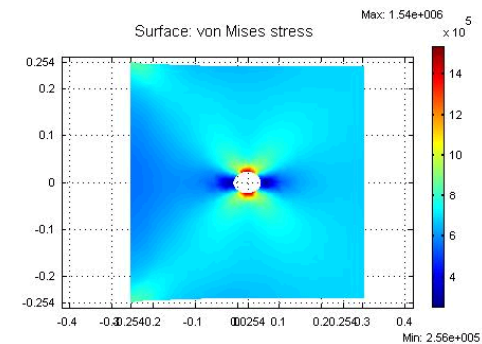
meshing, Ω^h



x displacement, u^h



y displacement, v^h



von Mises stress

S.12(CMn.23) Streamfunction-Vorticity Navier-Stokes

For $n = 2$: $\mathbf{u} = \nabla \times \psi \hat{\mathbf{k}}$ and $\omega \equiv \nabla \times \mathbf{u} \cdot \hat{\mathbf{k}}$

DM: $\nabla \cdot \mathbf{u} = \nabla \cdot \nabla \times \psi \hat{\mathbf{k}} = 0$ identically

$\hat{\mathbf{k}} \cdot \nabla \times \text{DP}$: $\omega_t + \nabla \times \psi \hat{\mathbf{k}} \cdot \nabla \omega - \text{Re}^{-1} \nabla^2 \omega = 0$

kinematics: $\omega = \nabla \times \mathbf{u} \cdot \hat{\mathbf{k}} = \nabla \times \nabla \times \psi \hat{\mathbf{k}} \cdot \hat{\mathbf{k}} = -\nabla^2 \psi$

Steady-state N-S PDEs + BCs:

$$\mathcal{L}(\omega) = -\text{Re}^{-1} \nabla^2 \omega + \nabla \times \psi \hat{\mathbf{k}} \cdot \nabla \omega = 0$$

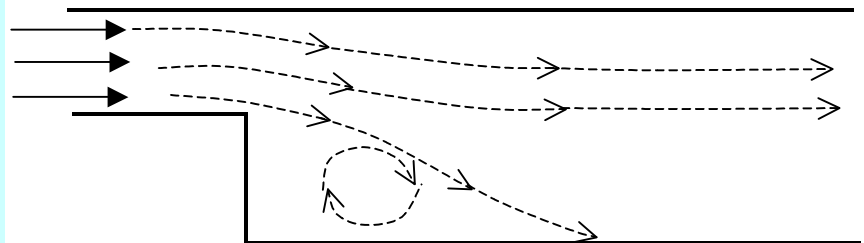
$$\mathcal{L}(\psi) = -\nabla^2 \psi - \omega = 0$$

$\partial\Omega_{\text{in}}$: $\mathbf{u}(y, x_{\text{in}}) \Rightarrow \omega_{\text{in}}, \psi_{\text{in}}$ via definitions

$\partial\Omega_{\text{out}}$: $\hat{\mathbf{n}} \cdot \nabla(\omega, \psi) = 0$

$\partial\Omega_{\text{wall}}$: $\psi = \psi_w = \text{constant}$

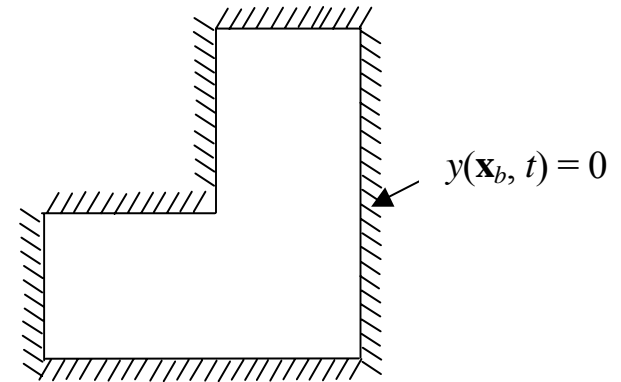
$\hat{\mathbf{n}} \cdot \nabla \omega = f_w(\psi, \omega)$



S.13(CMn.31) Mechanical Vibrations Normal Modes

Transverse vibrations of a plate

$$\text{dP: } \frac{\partial^2 y}{\partial t^2} - \nabla \cdot f(E, \nu) \nabla y = 0$$



normal mode solution

$$y(\mathbf{x}, t) = Q(\mathbf{x}) e^{i\omega t}$$

GWS^h for eigenmodes

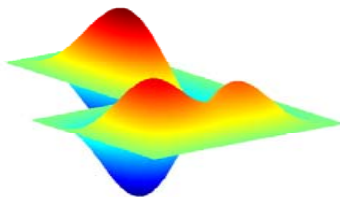
$$[[\text{STIFF}] - \omega^2 [\text{MASS}]] \{Q\} = \{0\}$$

homogeneous BCs

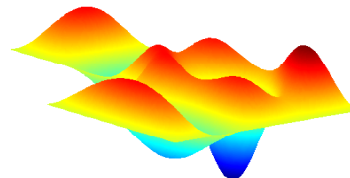
$$\det([\text{MASS}]^{-1} [\text{STIFF}] - \omega_i^2 [\text{I}]) = \{0\}$$

GWS^h normal mode solutions, $\omega_i^h = 45, 71, 99$ for $i = 7, 12, 19$

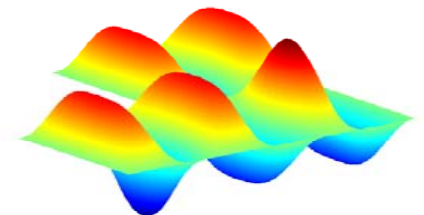
lambda(7)=44.9498 Surface: u (u) Height: u (u)



Lambda(12)=71.0795 Surface: u (u) Height: u (u)



lambda(19)=98.7051 Surface: u (u) Height: u (u)



S.14(FE.1) Engineering Simulation

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Computational Laboratory:

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